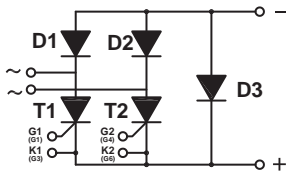


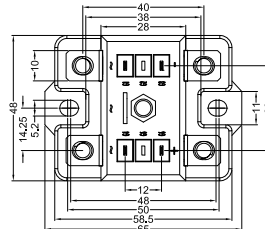
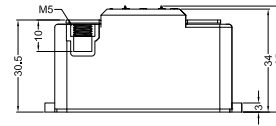
# S1PHB41GKXXB

## Single Phase Half Controlled Bridge Modules With Free Wheeling Diode



Type	$V_{RSM}$ $V_{DSM}$ V	$V_{RRM}$ $V_{DRM}$ V
<b>S1PHB41GK08B</b>	900	800
<b>S1PHB41GK12B</b>	1300	1200
<b>S1PHB41GK14B</b>	1500	1400
<b>S1PHB41GK16B</b>	1700	1600
<b>S1PHB41GK18B</b>	1900	1800

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit
$I_{dAV}$ $I_{dAVM}$ $I_{FRMS}, I_{TRMS}$	$T_K=85^{\circ}C$ , module module per leg	40 40 31	A
$I_{TSM}, I_{FSM}$	$T_{VJ}=45^{\circ}C$ $V_R=0$ t=10ms (50Hz), sine t=8.3ms (60Hz), sine $T_{VJ}=T_{VJM}$ $V_R=0$ t=10ms(50Hz), sine t=8.3ms(60Hz), sine	430 460 380 430	A
$I^2t$	$T_{VJ}=45^{\circ}C$ $V_R=0$ t=10ms (50Hz), sine t=8.3ms (60Hz), sine $T_{VJ}=T_{VJM}$ $V_R=0$ t=10ms(50Hz), sine t=8.3ms(60Hz), sine	1200 1440 960 1150	A <sup>2</sup> s
$(di/dt)_{cr}$	$T_{VJ}=125^{\circ}C$ f=50Hz, $t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.3A$ $di_G/dt=0.3A/\mu s$ repetitive, $I_T=40A$ non repetitive, $I_T=1/2I_{dAV}$	150 500	A/ $\mu s$
$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM}$ ; $R_{GK}=\infty$ ; method 1 (linear voltage rise) $V_{DR}=2/3V_{DRM}$	1000	V/ $\mu s$
$P_{GM}$	$T_{VJ}=T_{VJM}$ $I_T=I_{TAVM}$ $t_p=30\mu s$ $t_p=500\mu s$	10 5	W
$P_{GAVM}$		0.5	W
$V_{RGM}$		10	V
$T_{VJ}$ $T_{VJM}$ $T_{stg}$		-40...+125 125 -40...+125	$^{\circ}C$
$V_{ISOL}$	50/60Hz, RMS $I_{ISOL} \leq 1mA$ t=1min t=1s	2500 3000	V~
$M_d$	Mounting torque (M5) Terminal connection torque (M5)	5±15% 5±15%	Nm Nm
Weight	typical	165	g



# S1PHB41GKXXB

## Single Phase Half Controlled Bridge Modules With Free Wheeling Diode

Symbol	Test Conditions	Characteristic Values	Unit
$I_R, I_D$	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	4	mA
$V_T$	$I_T=62A; T_{VJ}=25^{\circ}C$	1.64	V
$V_{TO}$	For power-loss calculations only	0.88	V
$r_T$		13	$m\Omega$
$V_{GT}$	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	1.5 1.6	V
$I_{GT}$	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	100 200	mA
$V_{GD}$	$T_{VJ}=T_{VJM};$ $V_D=2/3V_{DRM}$	0.2	V
$I_{GD}$		5	mA
$I_L$	$t_p=10\mu s; I_G=0.45A;$ $di_G/dt=0.45A/\mu s$ $T_{VJ}=25^{\circ}C$	450	mA
$I_H$	$T_{VJ}=25^{\circ}C; V_D=6V; R_{GK}=\infty$	200	mA
$t_{gd}$	$T_{VJ}=25^{\circ}C; V_D=1/2V_{DRM}$ $I_G=0.45A; di_G/dt=0.45A/\mu s$	2	$\mu s$
$t_q$	$T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; V_R=100V$ $V_D=2/3V_{DRM}; dv/dt=15V/\mu s; di/dt=-10A/\mu s$ typ.	250	$\mu s$
$R_{thJC}$	per thyristor/Diode; DC per module	0.98 0.196	K/W
$R_{thJK}$	per thyristor/Diode; DC per module	1.20 0.24	K/W
$d_s$	Creeping distance on surface	16.1	mm
$d_A$	Creepage distance in air	7.1	mm
$a$	Maximum allowable acceleration	50	$m/s^2$



# S1PHB41GKXX

## Single Phase Half Controlled Bridge Modules With Free Wheeling Diode

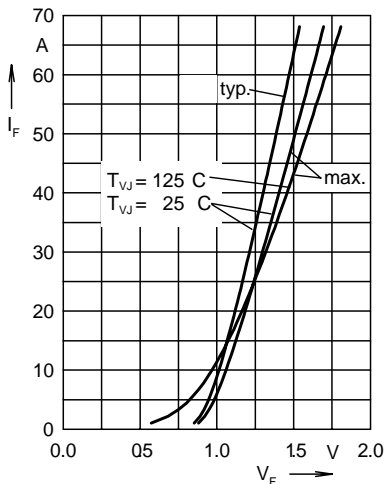


Fig. 3 Forward current versus voltage drop per diode

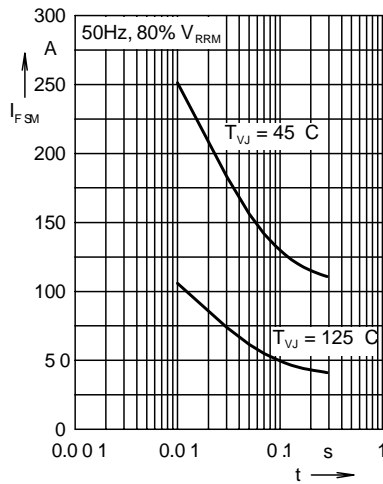


Fig. 4 Surge overload current

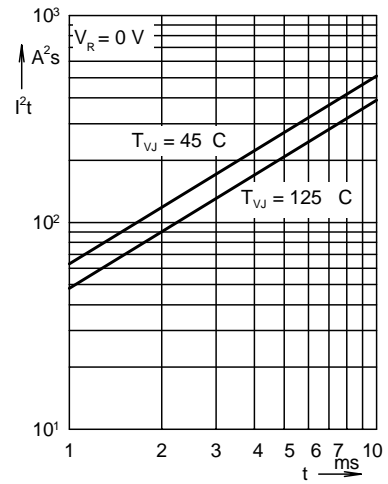


Fig. 5  $i^2t$  versus time per diode

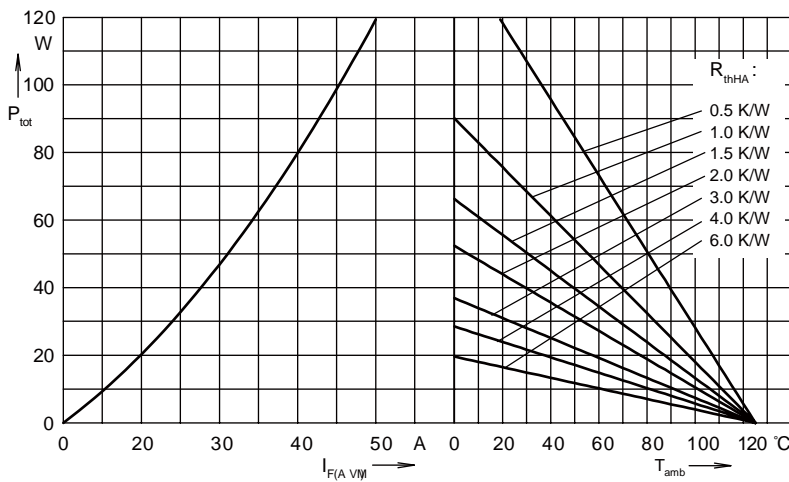


Fig. 6 Power dissipation versus direct output current and ambient temperature

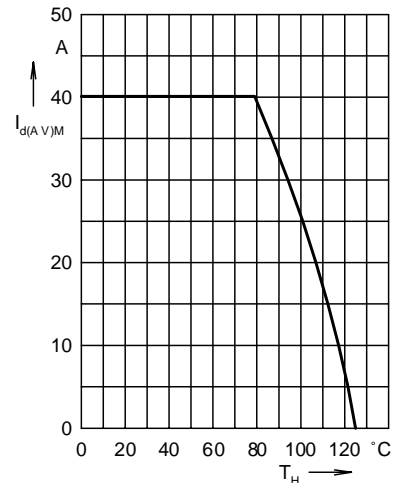


Fig. 7 Max. forward current versus heatsink temperature

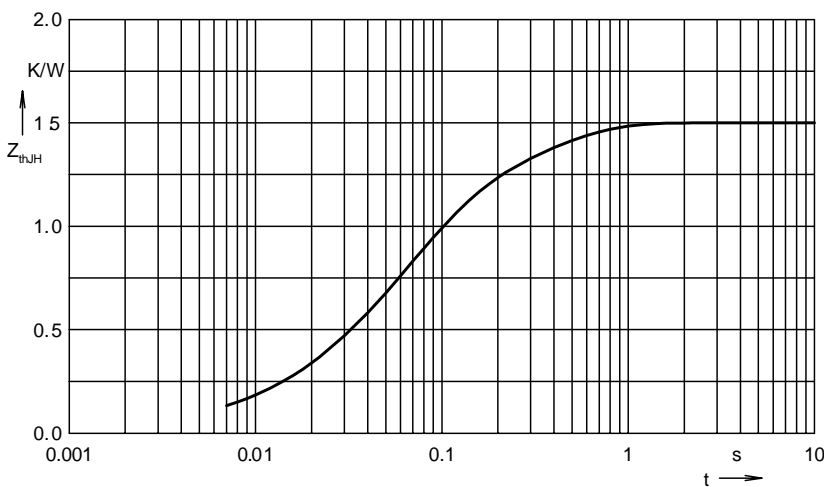


Fig. 8 Transient thermal impedance junction to heatsink

Constants for  $Z_{thJH}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.005	0.008
2	0.2	0.05
3	0.875	0.06
4	0.47	0.25