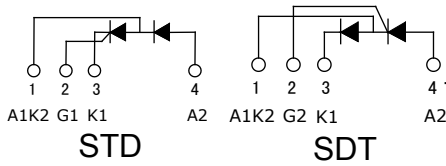
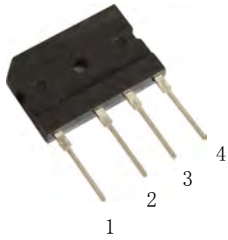


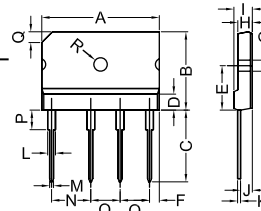
# STD25GXXP

## Thyristor-Diode Modules



Dimensions in mm (1mm=0.0394")

| Type      | $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V |
|-----------|-----------------------------|-----------------------------|
| STD25G08P | 900                         | 800                         |
| STD25G12P | 1300                        | 1200                        |
| STD25G14P | 1500                        | 1400                        |
| STD25G16P | 1700                        | 1600                        |
| STD25G18P | 1900                        | 1800                        |



| DIM. | GBJ       |       |
|------|-----------|-------|
|      | MIN.      | MAX.  |
| A    | 29.70     | 30.30 |
| B    | 19.70     | 20.30 |
| C    | 17.0      | 18.0  |
| D    | 4.70      | 4.90  |
| E    | 10.80     | 11.20 |
| F    | 2.30      | 2.70  |
| G    | 3.10      | 3.40  |
| H    | 3.40      | 3.80  |
| I    | 4.40      | 4.80  |
| J    | 2.50      | 2.90  |
| K    | 0.60      | 0.80  |
| L    | 2.00      | 2.40  |
| M    | 0.90      | 1.10  |
| N    | 9.80      | 10.20 |
| O    | 7.30      | 7.70  |
| P    | 3.80      | 4.20  |
| Q    | (3.0)X45° |       |
| R    | Φ3.10     | Φ3.40 |

| Symbol                                       | Test Conditions  | Maximum Ratings                       | Unit             |
|--|--|---------------------------------------|------------------|
| $I_{TRMS}, I_{FRMS}$<br>$I_{TAVM}, I_{FAVM}$ | $T_{VJ}=T_{VJM}$<br>$T_C=85^{\circ}C; 180^{\circ}$ sine  | 40<br>25                              | A                |
| $I_{TSM}, I_{FSM}$                           | $T_{VJ}=45^{\circ}C$<br>$V_R=0$<br>$t=10ms$ (50Hz), sine<br>$t=8.3ms$ (60Hz), sine               | 420<br>460                            | A                |
|  | $T_{VJ}=T_{VJM}$<br>$V_R=0$<br>$t=10ms$ (50Hz), sine<br>$t=8.3ms$ (60Hz), sine                   | 360<br>400                            |                  |
| $\int i^2 dt$                                | $T_{VJ}=45^{\circ}C$<br>$V_R=0$<br>$t=10ms$ (50Hz), sine<br>$t=8.3ms$ (60Hz), sine               | 1350<br>1300                          | A <sup>2</sup> s |
|  | $T_{VJ}=T_{VJM}$<br>$V_R=0$<br>$t=10ms$ (50Hz), sine<br>$t=8.3ms$ (60Hz), sine                   | 1050<br>1030                          |                  |
| $(di/dt)_{cr}$                               | $T_{VJ}=T_{VJM}$<br>$f=50Hz, t_p=200us$<br>$V_D=2/3V_{DRM}$<br>$I_G=0.45A$<br>$di_G/dt=0.45A/us$ | repetitive, $I_T=45A$<br>150          | A/us             |
|  |  | non repetitive, $I_T=I_{TAVM}$<br>500 |                  |
| $(dv/dt)_{cr}$                               | $T_{VJ}=T_{VJM};$<br>$R_{GK}=\infty;$ method 1 (linear voltage rise)                             | $V_{DR}=2/3V_{DRM}$<br>1000           | V/us             |
| $P_{GM}$                                     | $T_{VJ}=T_{VJM}$<br>$I_T=I_{TAVM}$   | $t_p=30us$<br>10                      | W                |
|  |  | $t_p=300us$<br>5                      |                  |
| $P_{GAV}$                                    |  | 0.5                                   | W                |
| $V_{RGM}$                                    |  | 10                                    | V                |
| $T_{VJ}$<br>$T_{VJM}$<br>$T_{stg}$           |  | -40...+125                            | °C               |
|  |  | 125                                   |                  |
|  |  | -40...+125                            |                  |
| $V_{ISOL}$                                   | 50/60Hz, RMS<br>$I_{ISOL} \leq 1mA$  | $t=1min$<br>3000                      | V~               |
|  |  | $t=1s$<br>3600                        |                  |
| $M_d$  | Mounting torque (M3)   | 2.5-4.0/22-35                         | Nm/lb.in.        |
| Weight                                       | Typical including screws   | 6.6                                   | g                |



# STD25GXXP

## Thyristor-Diode Modules

| Symbol             | Test Conditions  | Characteristic Values | Unit      |
|--------------------|--|-----------------------|-----------|
| $I_{RRM}, I_{DRM}$ | $T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$   | 2                     | mA        |
| $V_T, V_F$         | $I_T, I_F=25A; T_{VJ}=25^{\circ}C$   | 1.50                  | V         |
| $V_{TO}$           | For power-loss calculations only ( $T_{VJ}=125^{\circ}C$ )   | 0.85                  | V         |
| $r_T$              |  | 11                    | $m\Omega$ |
| $V_{GT}$           | $V_D=6V;$<br>$T_{VJ}=25^{\circ}C$<br>$T_{VJ}=-40^{\circ}C$   | 1.5<br>1.6            | V         |
| $I_{GT}$           | $V_D=6V;$<br>$T_{VJ}=25^{\circ}C$<br>$T_{VJ}=-40^{\circ}C$   | 100<br>200            | mA        |
| $V_{GD}$           | $T_{VJ}=T_{VJM};$<br>$V_D=2/3V_{DRM}$  | 0.2                   | V         |
| $I_{GD}$           |  | 10                    | mA        |
| $I_L$              | $T_{VJ}=25^{\circ}C; t_p=10\mu s; V_D=6V$<br>$I_G=0.45A; di_G/dt=0.45A/\mu s$                            | 450                   | mA        |
| $I_H$              | $T_{VJ}=25^{\circ}C; V_D=6V; R_{GK}=\infty$  | 200                   | mA        |
| $t_{gd}$           | $T_{VJ}=25^{\circ}C; V_D=1/2V_{DRM}$<br>$I_G=0.45A; di_G/dt=0.45A/\mu s$                                 | 2                     | $\mu s$   |
| $t_q$              | $T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; -di/dt=10A/\mu s$<br>$V_R=100V; dv/dt=20V/\mu s; V_D=2/3V_{DRM}$ | 150                   | $\mu s$   |
| $Q_S$              | $T_{VJ}=T_{VJM}; I_T, I_F=25A; -di/dt=0.64A/\mu s$   | 50                    | $\mu C$   |
| $I_{RM}$           |  | 6                     | A         |
| $R_{thJC}$         | per thyristor/diode; DC current<br>per module  | 1.68<br>0.84          | K/W       |
| $R_{thJK}$         | per thyristor/diode; DC current<br>per module  | 1.94<br>0.97          | K/W       |
| $d_s$              | Creeping distance on surface   | 12.7                  | mm        |
| $d_A$              | Strike distance through air  | 9.6                   | mm        |
| $a$                | Maximum allowable acceleration   | 50                    | $m/s^2$   |

### FEATURES

- \* Ideal for printed circuit board
- \* Isolation voltage 3600 V~
- \* Reliable low cost construction utilizing molded plastic technique results in inexpensive product

### APPLICATIONS

- \* DC motor control
- \* Softstart AC motor controller
- \* Light, heat and temperature control

### ADVANTAGES

- \* Space and weight savings
- \* Simple mounting with single screws
- \* Improved temperature and power cycling
- \* Reduced protection circuits

