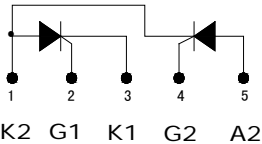
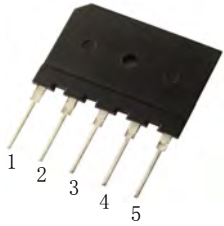


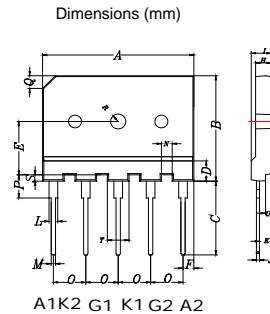
# STT25G\*\*P

## Thyristor-Thyristor Modules



### Dimensions in mm (1mm=0.0394")

Type	$V_{RSM}$ $V_{DSM}$ V	$V_{RRM}$ $V_{DRM}$ V
STT25G08P	900	800
STT25G12P	1300	1200
STT25G14P	1500	1400
STT25G16P	1700	1600
STT25G18P	1900	1800



(mm)	MIN	TYP	MAX
A	34.70	35.0	35.30
B	24.70	25.0	25.30
C	17.0	17.50	18.0
D	4.70	4.80	4.90
E	12.45	12.65	12.85
F	2.30	2.50	2.70
G	3.10	3.25	3.40
H	3.40	3.60	3.80
I	4.40	4.60	4.80
J	2.50	2.70	2.90
K	0.60	0.70	0.80
L	2.0	2.20	2.40
M	0.90	1.0	1.10
N	2.50	2.60	2.90
O	7.30	7.50	7.70
P	5.40	5.50	5.60
Q		(3,0) × 45°	
R	∅3.10	∅3.25	∅3.40
S	1.40	1.50	1.60
T	4.60	4.80	5.0
U	1.20	1.30	1.40

Symbol	Test Conditions	Maximum Ratings	Unit
$I_{TRMS}, I_{FRMS}$	$T_{VJ}=T_{VJM}$	39	A
$I_{TAVM}, I_{FAVM}$	$T_C=85^{\circ}C; 180^{\circ}$ sine	25	
$I_{TSM}, I_{FSM}$	$T_{VJ}=45^{\circ}C$ $V_R=0$	$t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	A
	$T_{VJ}=T_{VJM}$ $V_R=0$	$t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	
$\int i^2 dt$	$T_{VJ}=45^{\circ}C$ $V_R=0$	$t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	A <sup>2</sup> s
	$T_{VJ}=T_{VJM}$ $V_R=0$	$t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	
$(di/dt)_{cr}$	$T_{VJ}=T_{VJM}$ $f=50Hz, t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.45A$ $di_G/dt=0.45A/\mu s$	repetitive, $I_T=25A$	150
		non repetitive, $I_T=I_{TAVM}$	500
$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM};$ $R_{GK}=\infty;$ method 1 (linear voltage rise)	$V_{DR}=2/3V_{DRM}$	1000
$P_{GM}$	$T_{VJ}=T_{VJM}$ $I_T=I_{TAVM}$	$t_p=30\mu s$ $t_p=300\mu s$	10 5
$P_{GAV}$			0.5
$V_{RGM}$			10
$T_{VJ}$ $T_{VJM}$ $T_{stg}$			-40...+125 125 -40...+125
$V_{ISOL}$	50/60Hz, RMS $I_{ISOL} \leq 1mA$	$t=1min$ $t=1s$	3000 3600
$M_d$	Mounting torque (M3)		0.8-1.2/7-11
Weight	Typical including screws		15



# STT25G\*\*P

## Thyristor-Thyristor Modules

Symbol	Test Conditions	Characteristic Values	Unit
$I_{RRM}, I_{DRM}$	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	2	mA
$V_{TA}$ .....	$I_{TM}=80A; T_{VJ}=25^{\circ}C$	1.64	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ}=125^{\circ}C$ )	0.85	V
$r_T$		11	$m\Omega$
$V_{GT}$	$V_D=6V; T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	1.5 1.6	V
$I_{GT}$	$V_D=6V; T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	100 200	mA
$V_{GD}$	$T_{VJ}=T_{VJM}; V_D=2/3V_{DRM}$	0.2	V
$I_{GD}$		10	mA
$I_L$	$T_{VJ}=25^{\circ}C; t_p=10\mu s; V_D=6V$ $I_G=0.45A; di_G/dt=0.45A/\mu s$	450	mA
$I_H$	$T_{VJ}=25^{\circ}C; V_D=6V; R_{GK}=\infty$	200	mA
$t_{gd}$	$T_{VJ}=25^{\circ}C; V_D=1/2V_{DRM}$ $I_G=0.45A; di_G/dt=0.45A/\mu s$	2	$\mu s$
$t_q$	$T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; -di/dt=10A/\mu s$ $V_R=100V; dv/dt=20V/\mu s; V_D=2/3V_{DRM}$	150	$\mu s$
$Q_S$	$T_{VJ}=T_{VJM}; I_T, I_F=25A; -di/dt=0.64A/\mu s$	50	$\mu C$
$I_{RM}$		6	A
$R_{thJC}$	per thyristor/diode; DC current per module	1.62 0.81	K/W
$R_{thJK}$	per thyristor/diode; DC current per module	1.88 0.94	K/W
$d_s$	Creeping distance on surface	12.7	mm
$d_A$	Strike distance through air	9.6	mm
$a$	Maximum allowable acceleration	50	$m/s^2$

### FEATURES

- \* Ideal for printed circuit board
- \* Isolation voltage 3000 V~
- \* Reliable low cost construction utilizing molded plastic technique results in inexpensive product
- \* RoHS Compliant

### APPLICATIONS

- \* DC motor control
- \* Softstart AC motor controller
- \* Light, heat and temperature control

### ADVANTAGES

- \* Space and weight savings
- \* Simple mounting with single screws
- \* Improved temperature and power cycling
- \* Reduced protection circuits



www.sirectifier.com